

SKIEW FRACTIONAL BROWNIAN MOTION AND STOCHASTIC SEWING WITH CONTROLS

Oleg Butkovsky

Joint work with



Siva Athreya



Khoa Le



Leonid Mytnik

Weierstrass institute

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Plan of the talk

- ▶ Skew random walk and skew Brownian motion
- ▶ Skew fractional Brownian motion and skew stochastic heat equation
- ▶ Sewing of [Gubinelli](#) and sewing with controls of [Friz–Zhang](#)
- ▶ [Veretennikov–Zvionkin](#) transformation vs stochastic sewing with controls

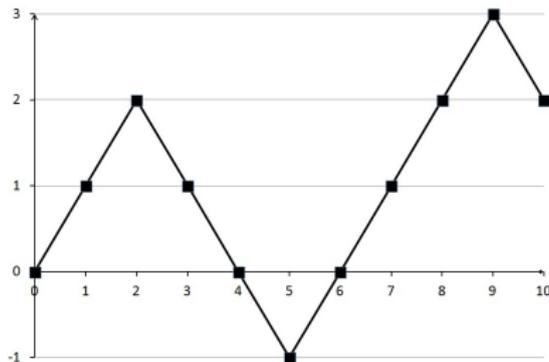
Skew random walk and skew Brownian motion

α -skew simple random walk

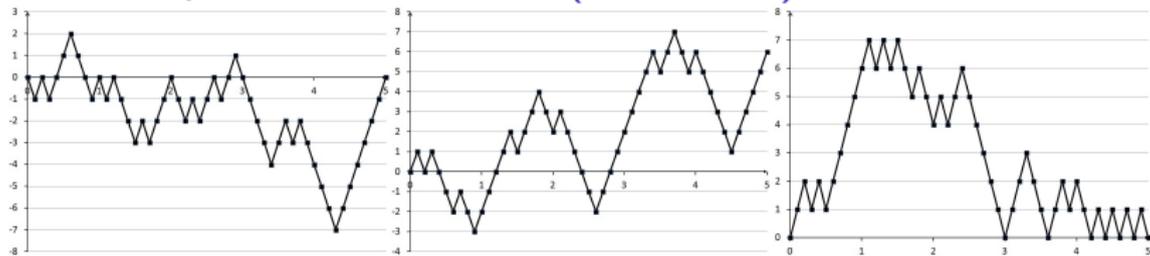
Fix $\alpha \in [0, 1]$ and consider the following simple Markov process

$(S_n)_{n \in \mathbb{Z}_+}$:

- ▶ $S_0 = 0$;
- ▶ $P(S_{n+1} = i + 1 | S_n = i) = P(S_{n+1} = i - 1 | S_n = i) = 1/2$ if $i \neq 0$;
- ▶ $P(S_{n+1} = 1 | S_n = 0) = \alpha$;
- ▶ $P(S_{n+1} = -1 | S_n = 0) = 1 - \alpha$.



α -skew simple random walk (α -SSRW)

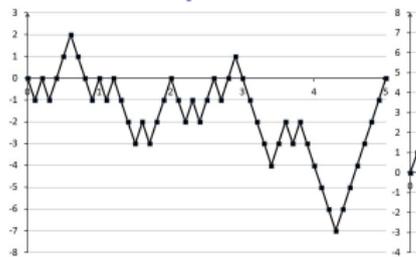


$\alpha = 0.2$

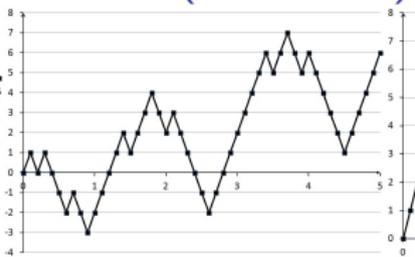
$\alpha = 0.5$

$\alpha = 0.8$

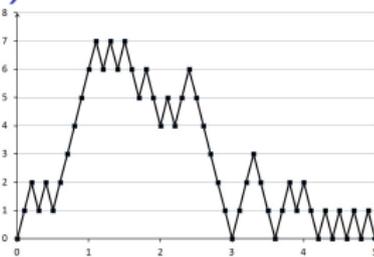
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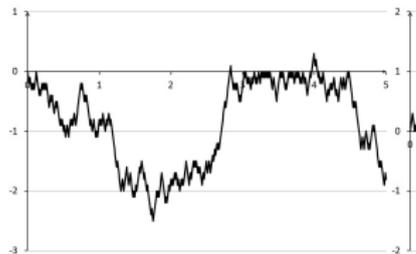


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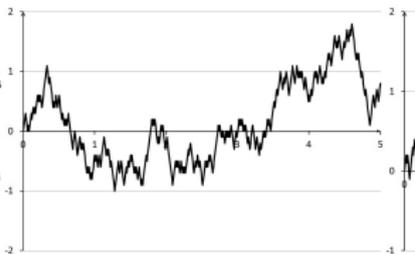


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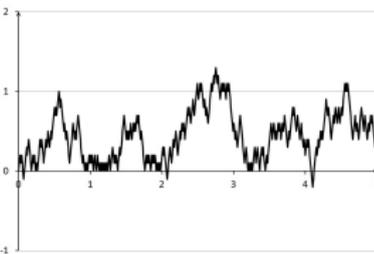
- **Harisson** and **Shepp** (1981) showed that a properly rescaled α -SSRW converges to an α -skew *Brownian motion*



$\alpha = 0.2$



$\alpha = 0.5$



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More on α -skew Brownian motion (α -SBM)

- ▶ Harisson and Shepp: $n^{-1/2}S_{\lfloor n \cdot \rfloor} \rightarrow X^{(\alpha)}$, where $X^{(\alpha)}$ is α -SBM.
- ▶ One can construct an α -SSRW in the following way: take SRW and change independently the sign of its excursions: each excursion is positive with probability α and negative with probability $1 - \alpha$.

More on α -skew Brownian motion (α -SBM)

- ▶ Harisson and Shepp: $n^{-1/2}S_{\lfloor n \rfloor} \rightarrow X^{(\alpha)}$, where $X^{(\alpha)}$ is α -SBM.
- ▶ One can construct an α -SSRW in the following way: take SRW and change independently the sign of its excursions: each excursion is positive with probability α and negative with probability $1 - \alpha$.
- ▶ The same is true for an α -SBM (Ito, McKean, 1965): take BM and change independently the sign of its excursions: each excursion is positive with probability α and negative with probability $1 - \alpha$.
- ▶ In particular, if $\alpha = 0.5$, $X^{(\alpha)}$ is a standard BM; if $\alpha = 1$, $X^{(\alpha)}$ is a reflected BM.

More on α -skew Brownian motion (α -SBM)

- ▶ It is clear that α -SBM is not a martingale and not Gaussian for $\alpha \neq 0.5$.
- ▶ However, it is still a diffusion process! It satisfies the following SDE:

$$X^{(\alpha)}(t) = \beta \int_0^t \delta(X_s^{(\alpha)}) ds + W_t, \quad (*)$$

where $\beta := 2\alpha - 1$.

Theorem (Harisson, Shepp, 1981)

If $\beta \in [-1, 1]$ SDE () has a unique strong solution. This solution has the same law as α -SBM.*

SDE for skew BM

$$X^{(\alpha)}(t) = \beta \int_0^t \delta(X_s^{(\alpha)}) ds + W_t, \quad (*)$$

- ▶ Since δ is not a function but just a distribution, $\delta(X_t)$ is a priori not well-defined.
- ▶ We say that a process X solves SDE (*) if $X = W + \psi$ and one has

$$\sup_{t \in [0,1]} \left| \psi_t - \beta \int_0^t p_\varepsilon(X_s) ds \right| \rightarrow 0,$$

in probability as $\varepsilon \rightarrow 0$.

- ▶ Here p_ε is a Gaussian kernel with mean 0 and variance ε , however the choice of a sequence of functions approximating δ is not important.

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- ▶ Here p_ε is a Gaussian kernel with mean 0 and variance ε , however the choice of a sequence of functions approximating δ is not important.
- ▶ What if $|\beta| > 1$? Maybe (*) would still have a solution?

Theorem (Harisson, Shepp, 1981)

If $|\beta| > 1$ then SDE () does not have even a weak solution.*

Warm-up (reminder)

$$X^{(\alpha)}(t) = \beta \int_0^t \delta(X_s^{(\alpha)}) ds + W_t, \quad (*)$$

- ▶ Let's show that this SDE has a weak solution for $\beta = 1$.
- ▶ Take $X_t := |B_t|$, where B is a Brownian motion. Then by Ito's formula (informally)

$$dX_t = d|B_t| = \text{sign}(X_t)dB_t + \delta(X_t)dt = dM_t + \delta(X_t)dt,$$

where $M_t := \int_0^t \text{sign}(X_t)dB_t$. Since $\langle M \rangle_t = t$, we see that M is a BM.

- ▶ Thus the pair $(|B|, M)$ is indeed a weak solution to $(*)$.

SDE for Skew BM

$$X^{(\alpha)}(t) = \beta \int_0^t \delta(X_s^{(\alpha)}) ds + W_t, \quad (*)$$

- ▶ In the general case $|\beta| \neq 1$ [Harisson–Shepp](#) applied the [Veretennikov-Zvonkin](#) method.
- ▶ They construct a nice function F such that the process $Y_t := F(X_t)$, does not have a drift and satisfy a nice SDE

$$dY(t) = G(Y_s) dW_s,$$

where G is not too bad. Then from uniqueness/non-existence of solutions to this SDE one can show uniqueness/non-existence of solutions to the original equation.

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- ▶ This method was pioneered by [Veretennikov](#), [Zvonkin](#) in 1970ies for showing well-posedness of SDEs with bounded drift, and later developed by [Flandolli](#), [Gubinelli](#), [Priola](#), [Bass](#), etc.
- ▶ **To apply this method one needs Ito's formula!**

Skew fractional Brownian motion and skew stochastic heat equation

Skew fractional Brownian motion (SfBM)

- ▶ Consider now **fractional** Brownian motion W^H , $H \in (0, 1)$.
- ▶ Recall that W^H is a Gaussian process with mean 0 and covariance $\mathbb{E}W_t^H W_s^H = \frac{1}{2}(t^{2H} + s^{2H} - |t - s|^{2H})$.
- ▶ Its trajectories are Hölder with the exponent H – a.s.
- ▶ For $H = 1/2$ fBM is just BM; for $H \neq 1/2$ it is not a Markov process nor a semimartingale.
- ▶ Ito's formula is not available here.
- ▶ We want to define a skew fractional Brownian motion by analogy with SBM.

Skew fractional Brownian motion (SfBM)

- ▶ We cannot define SfBM as a limit of a random walk model.
- ▶ We cannot define SfBM by flipping its excursions, because fBM is not a Markov process.
- ▶ Thus, the only hope is to define SfBM via the corresponding SDE.

Definition

The unique strong solution to the following SDE will be called SfBM:

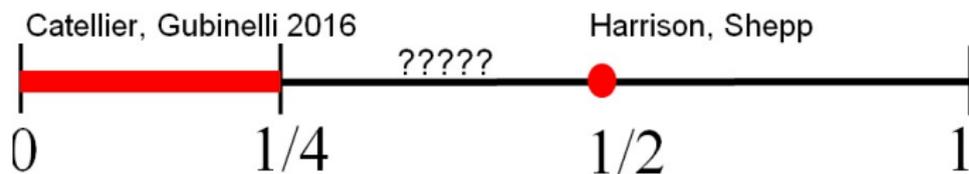
$$X(t) = \beta \int_0^t \delta(X_s) ds + W_t^H. \quad (**)$$

- ▶ Does sFBM exist?

Skew fractional Brownian motion (SfBM)

$$X(t) = \beta \int_0^t \delta(X_s) ds + W_t^H. \quad (**)$$

- ▶ It is known that (**) has a unique strong solution in the red intervals of the plot below; $1/4$ is **not** included.

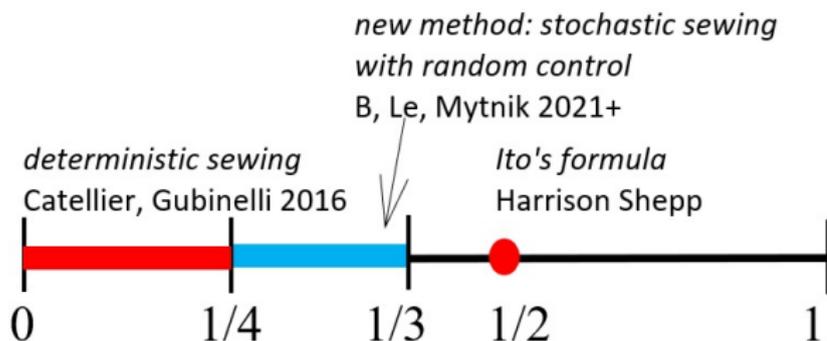


- ▶ Heuristically, the more irregular the driving noise, the rougher the drift can be.
- ▶ The bound $1/4$ does not have any special meaning; it is known that if $H < 1/4$ then SDE (**) has a unique strong solution for any drift in \mathcal{C}^{-1} .
- ▶ But δ is also a measure!

Main result and conjecture

$$X(t) = \beta \int_0^t \delta(X_s) ds + W_t^H. \quad (**)$$

- ▶ The gap appears because Ito's formula is not available for $H \neq 1/2$ and one has to develop other methods to solve this problem.



- ▶ Conjecture: equation (**) has a unique strong solution if $H < 1/2$ and no weak solutions if $H > 1/2$.

Skew stochastic heat equation

- ▶ The fact that now we are able to cover the case $H = 1/4$ allows to show that the *skew stochastic heat equation* is well-defined.
- ▶ This process was conjectured to exist by [Bounebacher, Zambotti, 2011](#).

$$\partial_t u = \partial_{xx} u + \beta \delta(u) + \dot{W}, \quad t \geq 0, \quad x \in \mathbb{R},$$

where \dot{W} is a space-time white-noise.

Skew stochastic heat equation

$$\partial_t u = \partial_{xx} u + \beta \delta(u) + \dot{W}, \quad t \geq 0, \quad x \in \mathbb{R},$$

As usual, we say that u solves this equation if

$$\begin{aligned} u(t, x) = & p_t * u_0(x) \\ & + \int_0^t \int_{\mathbb{R}} \beta p_{t-s}(x - x') \delta(u(s, x')) dx' ds + V(t, x) \end{aligned}$$

where p is the standard heat kernel and

$$V(t, x) := \int_0^t \int_{\mathbb{R}} p_{t-s}(x - x') W(ds, dx').$$

- ▶ For fixed $x \in \mathbb{R}$ the process $V(t)$ “behaves like” fBM 1/4. Thus, the following theorem holds.

Theorem (ABLM, 2021)

For any $\beta \in \mathbb{R}$ skew stochastic heat equation has a unique strong solution.

Sewing of Gubinelli and sewing with controls of Friz–Zhang

Proof idea: big picture

- ▶ To fix the ideas consider 1D SDE with “bad” drift $b \in \mathcal{C}^\gamma$, $\gamma < 1$.

$$dX_t = b(X_t)dt + dW_t.$$

- ▶ Let us try to prove strong uniqueness of solutions to this equation. Let X and \tilde{X} be two solutions to this equation. Denote $Z := \tilde{X} - X$. We have

$$\|Z_t\|_{L_p} = \left\| \int_0^t [b(\tilde{X}_s) - b(X_s)] ds \right\|_{L_p}$$

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- ▶ At least we want to show that

$$\left\| \int_0^t [b(W_s + z) - b(W_s)] ds \right\|_{L_p} \leq Ct^\rho |z|.$$

Recall that for us $b = \delta$.

Sewing lemma of Gubinelli

- ▶ Let $f \in \mathcal{C}^\alpha$, $g \in \mathcal{C}^\beta$. Then it is well-known that $\int fdg$ exists and can be defined as a limit of Riemann sums if $\alpha + \beta > 1$.
- ▶ One way to prove it, is [Gubinelli's sewing lemma \(2004\)](#).

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- ▶ Suppose we are given a continuous (deterministic) process $A_{s,t}$, indexed by $0 \leq s \leq t \leq 1$.
- ▶ Define for $0 \leq s \leq u \leq t$ $\delta A_{s,u,t} := A_{s,t} - A_{s,u} - A_{u,t}$.

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Theorem (Gubinelli)

Assume that $|\delta A_{s,u,t}| \leq N|t - s|^{1+\varepsilon}$. Then the following process exists

$$\mathcal{A}_t := \lim \sum A_{t_i, t_{i+1}},$$

and $|\mathcal{A}_t - \mathcal{A}_s| \leq |A_{s,t}| + CN|t - s|^{1+\varepsilon}$.

- ▶ For the Young case we take $A_{s,t} := f_s(g_t - g_s)$. Then $|\delta A_{s,u,t}| = |f_s(g_t - g_s) - f_s(g_u - g_s) - f_u(g_t - g_u)| = |(f_s - f_u)(g_t - g_u)| \leq |t - s|^{\alpha+\beta}$.

Sewing lemma with controls of Friz–Zhang

- ▶ Take $f \in \mathcal{C}^\alpha$, where $\alpha > 0$ is very small, and $g(t) := t^\beta$, $\beta > 0$ is also very small. Then $g \in \mathcal{C}^\beta$, $\alpha + \beta < 1$, yet $\int_0^t f(s) ds^\beta = N \int_0^t f(s) s^{\beta-1} ds$ exists.

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- ▶ Following Friz–Zhang, we say that a nonnegative continuous function $\lambda(s, t)$, where $0 \leq s \leq t \leq 1$ is a *control* if

$$\lambda(s, u) + \lambda(u, t) \leq \lambda(s, t), \quad \text{for any } 0 \leq s \leq u \leq t \leq 1.$$

Theorem (Friz, Zhang, 2017)

Assume that $|\delta A_{s,u,t}| \leq N|t-s|^\rho \lambda(s, t)$, $\rho > 0$. Then the following process exists

$$\mathcal{A}_t := \lim \sum A_{t_i, t_{i+1}},$$

and $|\mathcal{A}_t - \mathcal{A}_s| \leq |\mathcal{A}_{s,t}| + C|t-s|^\rho \lambda(s, t)$.

How do we gain with sewing with controls?

Demo mode

- ▶ Suppose we want to get a good bound on $\mathcal{A}_t := \int_0^t f(s) ds^\beta$,
 $f \in \mathcal{C}^\alpha$, $\alpha + \beta < 1$.
- ▶ Set $A_{s,t} := f_s(t^\beta - s^\beta)$.

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- ▶ Then $\delta A_{s,u,t} = A_{s,t} - A_{s,u} - A_{u,t} = (f_t - f_s)(t^\beta - s^\beta)$.

$$|\delta A_{s,u,t}| \leq$$

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$$|\delta A_{s,u,t}| \leq |t - s|^\alpha |t - s|^\beta$$

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$$\begin{aligned} |\delta A_{s,u,t}| &\leq |t - s|^\alpha \cancel{|t - s|^\beta} \\ &\leq |t - s|^\alpha \lambda(s, t) \end{aligned}$$

where $\lambda(s, t) := t^\beta - s^\beta$ is indeed a control.

Stochastic sewing with random controls

$$X(t) = \beta \int_0^t \delta(X_s) ds + W_t^H;$$

$$X = \psi + W^H.$$

A couple of observations:

- ▶ ψ is increasing; thus $\lambda(s, t) := \psi_t - \psi_s$ is a *random* control (i.e. $\lambda(s, u) + \lambda(u, t) \leq \lambda(s, t)$ whenever $s \leq u \leq t$).
- ▶ But $\|\psi_t - \psi_s\|_{L_p(\Omega)}$ is **NOT** a control for $p > 1$:-).
- ▶ So one has to be very careful in extending Friz–Zhang to the stochastic setting so that the result is still useful.
- ▶ Recall: a very useful extension of Gubinelli to the stochastic setup is due to [Le, 2019](#).

Stochastic sewing with random controls

- ▶ We say that the process $\lambda(s, t, \omega)$ is a random control if $\lambda(s, u, \omega) + \lambda(u, t, \omega) \leq \lambda(s, t, \omega)$ a.s. whenever $s \leq u \leq t$.

Theorem (B., Mytnik, 2020)

Let $A_{s,t}$ be an \mathcal{F}_t -measurable random variable. Assume that for some $p \geq 2$, $\rho > 0$ one has

$$\begin{aligned} \|\delta A_{sut}\|_{L_p} &\leq K_1 |t - s|^{1/2 + \varepsilon} \\ |\mathbb{E}[\delta A_{sut} | \mathcal{F}_u]| &\leq K_2 |t - s|^\rho \lambda(s, t) \text{ a.s.} \end{aligned}$$

Then there exists a process B_{st} and a constant $C > 0$, such that the following holds:

$$\|\mathcal{A}_t - \mathcal{A}_s\|_{L_p} \leq \|A_{st}\|_{L_p} + CK_1 |t - s|^{1/2 + \varepsilon} + CK_2 |t - s|^\rho \|\lambda(s, t)\|_{L_p}.$$

Stochastic sewing with random controls: application (sketch)

$$X(t) = \beta \int_0^t \delta(X_s) ds + W_t^H;$$
$$X = \psi + W^H.$$

- ▶ We need to show that $\|\psi_t - \psi_s\|_{L_p} \leq |t - s|^\gamma$.
- ▶ Recall that if $H = 1/2$, b is bounded, then this step is immediate; but already for $H = 1/2$, $b \in L_p$ this is not trivial.

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- ▶ Recall that if $H = 1/2$, b is bounded, then this step is immediate; but already for $H = 1/2$, $b \in L_p$ this is not trivial.
- ▶ Take $A_{s,t} := \int_s^t \delta(W_r^H + \psi_s) dr$.
- ▶ Then $\delta A_{sut} = \int_u^t \delta(W_r^H + \psi_u) - \delta(W_r^H + \psi_s) ds$.
- ▶ Hence $|\mathbb{E}[\delta A_{sut} | \mathcal{F}_u]| \leq |t - s|^\gamma |\psi_u - \psi_s|$ - which is very good!

Further directions:
conjectures/paradoxes/open problems

Open problems

- ▶ Well-posedness of $dX_t = \delta_0(X_t)dt + dW_t^H$, $H \in (1/3, 1/2)$.
- ▶ Weak existence and uniqueness?
- ▶ Numerics for SDEs driven by α -stable processes. We are planning to improve [Mikulevicius–Xu, 2016](#).

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- ▶ B., Le, Zambotti (work in progress). Consider SPDE on $[0, 1]$ with Dirichlet BC

$$\partial_t u = \frac{1}{2} \partial_{xx} u + \nabla f(u) + \dot{W}.$$

It's invariant measure is the Gibbs measure given by

$$\pi(A) := \frac{1}{Z} \int_A \int_0^1 e^{-f(x(z))} dz \mu(dx),$$

where μ is the law of the Brownian Bridge $0 \rightarrow 0$.

- ▶ Note that π is well-defined even if ∇f is a distribution! Can we take $\nabla f = \delta_0$?

Summary

- ▶ Harrison and Shepp using Veretennikov–Zvonikin technique showed that skew Brownian motion is well-defined.
- ▶ Extension of this to the fractional BM case is not easy! No Ito's formula.
- ▶ Catellier, Gubinelli used deterministic sewing to show that SfBM is well posed for $H < 1/4$.
- ▶ Inspired by sewing with controls of Friz–Zhang and stochastic sewing of Le, we developed stochastic sewing with controls.
- ▶ This allows to show well-posedness of SfBM for $H < 1/3$ and well-posedness of skew stochastic heat equation, thus resolving a conjecture of Bounebaché–Zambotti.
- ▶ The proofs are based on stochastic sewing and its variations, which we believe to be a very flexible and useful tool. We hope that one day it will become as popular as the Zvonkin–Veretennikov transform.