

Systems of forward and backward nonlinear Kolmogorov equations

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Aim : The aim of this talk is to discuss the possibility to reduce the Cauchy problem for systems of forward nonlinear parabolic equations (we call them forward Kolmogorov equations)

$$\begin{aligned} \frac{\partial u_m}{\partial t} = & \frac{1}{2} \sum_{i,j=1}^d G_{ij}(y, u) \nabla_{ji}^2 u_m + \sum_{l=1}^{d_1} \sum_{i=1}^d B_{ml}^i(y, u) \nabla_i u_l + \\ & + \sum_{l=1}^d c_{ml}(y, u) u_l, \end{aligned} \quad (1)$$

$$u_m(0, y) = u_{0m}(y), \quad m = 1, \dots, d_1,$$

$$\frac{\partial u_m}{\partial t} = \frac{1}{2} \sum_{i,j} \nabla_{ij}^2 \left[\sum_{l=1}^d [G^u]_{ij}^{ml}(y, u) u_l \right] - \nabla \cdot [a_m(y, u) u_m] + \sum_{l=1}^{d_1} c_{ml}^u(y) u_l, \quad (2)$$

with $G_{ij}(y) = \sum_{k=1}^d A_{ik}(y, u) A_{kj}(y, u)$, and $a \cdot b = \sum_k a_k b_k$ to correspondent stochastic problems.

Examples: Parabolic conservation and balance laws

$$\frac{\partial u}{\partial t} + \operatorname{div}[f(u)] = \operatorname{div}[G(u)\nabla u] + c(u)u, \quad u(0) = u_0,$$

$u \in R^{d_1}, f \in R^d \otimes R^{d_1}, G \in R^d \otimes R^d \otimes R^{d_1} \otimes R^{d_1}$ or $G \in R^d \otimes R^d$,
1) Shigesada, Kawasaki and Teramoto model of spatial segregation of interacting species (1979). (SKT-model) [1]

$$\frac{\partial u^m}{\partial t} = \Delta(u_m[\alpha_m + \alpha_{m1}u_1 + \alpha_{m2}u_2]) + c_m^u u^m,$$

$$u_m(0, x) = u_{0m}(x), \quad m = 1, 2,$$

where $c_m^u = c_m - c_{m1}u_1 - c_{m2}u_2$ and $\alpha_m, \alpha_{mk}, c_m, c_{mk}, m, k = 1, 2$ are positive constants.

2) Keller-Segel model in chemotaxis [2],

$$\frac{\partial u_1}{\partial t} = \Delta u_1 + \nabla \cdot (u_1 \nabla u_2) + c_1^u u_1,$$

$$\frac{\partial u_2}{\partial t} = \Delta u_2 + c_2^u u_2,$$

$$u_m(0, x) = u_{0m}(x), \quad m = 1, 2,$$

3) MHD-Burgers system [?]

$$\frac{\partial v}{\partial t} + v \cdot \nabla v = \frac{\sigma^2}{2} \Delta v + (\nabla \times B) \times B, \quad v(0, y) = v_0(y), \quad (3)$$

$$\frac{\partial B}{\partial t} = \frac{\mu^2}{2} \Delta B + \nabla \times (v \times B), \quad B(0, y) = B_0(y). \quad (4)$$

$B \in R^3$ is a magnetic field, $v \in R^3$ is the fluid velocity. (3) is the Burgers equation with pressure defined by the magnetic field.

Connections between nonlinear PDEs and SDEs are studied since seminal papers by **H.McKean** [4], [5] and **M.Freidlin** [6],[7].

$d_1 = 1$. 1) McKean (1966) A stochastic problem

$$d\xi(s) = \int_{R^d} a(\xi(s), y)\mu(s, dy)ds + \int_{R^d} A(\xi(s), y)\mu(s, dy)dw(s), \quad (5)$$

$$\mu(t) = \text{Law}(\xi(t)), \quad \xi(0) = \xi_0, \mu_0(dy) = P\{\xi(0) \in dy\}, \quad (6)$$

can be associated with the Cauchy problem

$$\frac{\partial \mu}{\partial t} = \frac{1}{2} \text{Tr} \nabla^2 \left[\int_{R^d} G(x, y)\mu(t, dy)\mu \right] - \nabla \cdot \left[\int_{R^d} a(x, y)\mu(t, dy)\mu \right], \quad (7)$$

$$\mu(0, dy) = \mu_0(dy),$$

where $\mu_0(y)dy = P\{\xi(0) \in dy\}$ $\text{Tr} \nabla^2 G = \sum_{i,j=1}^d \frac{\partial^2}{\partial x_i \partial x_j} G_{ji}$,
 $A(x, \mu) = \int_{R^d} \tilde{A}(x, y)\mu(dy)$, $G(x, \mu) = A(x, \mu)A^*(x, \mu)$ hence
 $A : R^d \times \mathcal{M}(R^d) \rightarrow R^d \otimes R^d$.

A different approach is due to Freidlin (1967). Namely, let coefficients $a(y, v)$, $A(y, v)$ be defined on $R^d \times R$. Then setting $v(T - t, x) = u(t, x)$ one can reduce the forward Cauchy problem

$$u_t = \frac{1}{2} \text{Tr} G(x, u(t, x)) \nabla^2 u + a(x, u(t, x)) \cdot \nabla u, \quad u(0, x) = u_0(x), \quad (8)$$

to the backward Cauchy problem

$$\frac{\partial v}{\partial t} + \frac{1}{2} \text{Tr} G(x, v(T - t, x)) \nabla^2 v + a(x, v(T - t, x)) \cdot \nabla v = 0, \quad (9)$$

$v(T, x) = u_0(x)$ and then to a stochastic problem

$$d\xi(\theta) = a(\xi(\theta), v(T - \theta, \xi(\theta))) d\theta + A(\xi(\theta), v(T - \theta, \xi(\theta))) dw(\theta), \quad \xi(t) = x \quad (10)$$

$$v(T - t, x) = E[u_0(\xi_{t,x}(T))]. \quad (11)$$

Freidlin's approach was extended to a wide class of quasilinear backward Kolmogorov equations and systems in papers by Yu.Dalecky and Bel. (1980 -1990) [8] – [10]. In particular, it was proved that the Cauchy problem

$$\frac{\partial u}{\partial t} + \frac{1}{2} \text{Tr} G(x, u(t, x)) \nabla^2 u + a(x, u(t, x)) \cdot \nabla u + c(x, u) u = 0, \quad (12)$$

$u(T, x) = u_0(x)$ can be reduced to a stochastic problem

$$d\xi(\theta) = a(\xi(\theta), u(\theta, \xi(\theta))) d\theta + A(\xi(\theta), u(\theta, \xi(\theta))) dw(\theta), \xi(t) = x, \quad (13)$$

$$u(t, x) = E \left[u_0(\xi_{t,x}(T)) \exp \left\{ \int_t^T c(\xi(\theta), u(\theta, \xi(\theta))) d\theta \right\} \right] \quad (14)$$

at least if we are interested in classical solutions of (12) and assume all coefficients and u_0 to be smooth enough.

Moreover it was proved that this approach works for systems

$$\frac{\partial \mathbf{u}_m}{\partial t} + \frac{1}{2} \text{Tr} \mathbf{G}(\mathbf{y}, \mathbf{v}) \nabla^2 \mathbf{u}_m + \sum_{l=1}^{d_1} \sum_{i=1}^d \mathbf{B}_{ml}^i(\mathbf{u}(t, \mathbf{y})) \nabla_i \mathbf{u}_l + \sum_{l=1}^{d_1} \mathbf{c}_{ml}(\mathbf{u}(t, \mathbf{y})) \mathbf{u}_l = 0, \quad u_m(T, y) = u_{0m}(y). \quad (15)$$

$m = 1, 2, \dots, d_1$, $G : R^d \times R^{d_1} \rightarrow R^d \otimes R^d$. Namely, one can reduce (12) to an associated stochastic system

$$d\xi(s) = A(u(s, \xi(s))) dw(s), \quad \xi(t) = x, \quad (16)$$

$$d\eta(s) = c(u(s, \xi(s))) \eta(s) ds + C(u(s, \xi(s))) \eta(s) dw(s), \quad \eta(t) = h, \quad (17)$$

$$h \cdot u(t, x) = E[\eta_{t,h}(T) \cdot u_0(\xi_{t,x}(T))], \quad (18)$$

setting $B = CA$.

Theorem 1. [9] *Assume that $a(x, u)$, $A(x, u)$ are C^3 -smooth bounded functions with sublinear growth in x and polilinear growth in u . Let $c(x, u)$, $C(x, u)$ be C^3 smooth function bounded in x and polylinear in u . Then there exists an interval $[T_1, T] \subset [0, T]$ such that:*

- 1) $\exists!$ *a unique solution to the system (16)-(18) defined on $[T_1, T]$;*
- 2) *the function v defined by (15) is a unique classical solution of the Cauchy problem (15) defined on $[T_1, T]$.*

Note that we can apply the above approach to a quasilinear scalar equation like a scalar nonlinear heat equation

$$\frac{\partial u}{\partial t} + \frac{1}{2} \frac{\partial}{\partial y} \left[u^2 \frac{\partial u}{\partial y} \right] + u^\beta = 0, \quad u(0, y) = u_0(y).$$

To this end we rewrite it as follows

$$\frac{\partial u}{\partial t} + \frac{1}{2} u^2 \frac{\partial^2 u}{\partial y^2} + u^\beta + g \frac{\partial u}{\partial y} = 0, \quad u(0, y) = u_0(y) \quad (19)$$

and introducing a new unknown function $g(t, y) = \frac{\partial}{\partial y} u(t, y)$ and derive an equation for g

$$\frac{\partial g}{\partial t} + \frac{1}{2} u^2 \frac{\partial^2 g}{\partial y^2} + 3ug \frac{\partial g}{\partial y} + g^3 + \beta u^{\beta-1} \frac{\partial u}{\partial x} = 0, \quad g(0, y) = \frac{\partial u_0(y)}{\partial y}. \quad (20)$$

Hence we obtain a system of the form (15) and can apply the above approach.

A similar trick with setting $v(T - t, x) = u(t, x)$ allows to go from (1) to (15) but it does not work for systems of the form (2).

To construct a probabilistic counterpart to the Cauchy problem (2) we have to find generators of corresponding Markov processes. We deduce it assuming that u satisfies

$$\begin{aligned} & \int_{\mathbb{R}^d} \mathbf{h}(\mathbf{t}, \mathbf{y}) \mathbf{u}_m(\mathbf{t}, \mathbf{y}) d\mathbf{y} - \int_{\mathbb{R}^d} \mathbf{h}(\mathbf{0}, \mathbf{y}) \mathbf{u}_{0m}(\mathbf{y}) d\mathbf{y} = \\ & = \int_0^t \int_{\mathbb{R}^d} \mathbf{u}_m(\mathbf{s}, \mathbf{y}) \left[\frac{\partial \mathbf{h}}{\partial \mathbf{s}} + \frac{1}{2} \text{Tr} \mathbf{G}_m^u(\mathbf{y}) \nabla^2 \mathbf{h}(\mathbf{y}) + \mathbf{a}_m^u \cdot \nabla \mathbf{h}(\mathbf{y}) + \right. \\ & \quad \left. + \mathbf{c}_m(\mathbf{u}, \nabla \mathbf{u}) \mathbf{h}(\mathbf{y}) \right] d\mathbf{y} ds, \end{aligned} \quad (21)$$

for any $h \in C_0^\infty([0, T] \times \mathbb{R}^d; \mathbb{R})$ and consider Markov processes with generators

$$\mathcal{L}_m^u \mathbf{h}(\mathbf{y}) = \frac{1}{2} \text{Tr} \mathbf{G}_m^u(\mathbf{x}) \nabla^2 \mathbf{h}(\mathbf{y}) + \mathbf{a}_m^u(\mathbf{x}) \cdot \nabla \mathbf{h}(\mathbf{y}). \quad (22)$$

Given a generator \mathcal{L}_m^u we consider SDEs

$$d\xi_m(\mathbf{s}) = \mathbf{a}_m^u(\xi_m(\mathbf{s})) d\mathbf{s} + \mathbf{A}_m^u(\xi_m(\mathbf{s})) d\mathbf{w}_m(\mathbf{s}), \quad \xi(\mathbf{0}) = \xi_0, \quad (23)$$

and observe that a remaining problem is to derive a closing relation.

To illustrate the approach we start with a simple version of a reaction - diffusion system

$$\frac{\partial u_1}{\partial t} = \frac{1}{2} M_1^2(y) \Delta u_1 + (c_{10} - c_{11} u_1 - c_{12} u_2) u_1, \quad (24)$$

$$\frac{\partial u_2}{\partial t} = \frac{1}{2} M_2^2(y) \Delta u_2 + (c_{20} - c_{21} u_1 - c_{22} u_2) u_2, \quad (25)$$

$$u_m(0) = u_{0m}.$$

We say (24), (25) has a (very) weak solution $u = (u_1, u_2)$ if $u_m(t) \in L^2(R^d)$ and for all $h \in C_0^\infty((0, T) \times R^d)$

$$\int_0^T \int_{R^d} u_m(t, y) \left[h_t + \frac{1}{2} M_m^2(t, y)^2 \Delta h(t, y) + c_m^u(t, y) h(t, y) \right] dy dt = 0, \quad (26)$$

hold with $c_m^u = c_{10} - c_{m1} u_1 - c_{m2} u_m$

Thus, we may consider $\xi_m(t)$ and $\eta_m(t)$, $m = 1, 2$, which satisfy

$$\xi_m(t) = \xi_{m0} + \int_0^t M_m(s, \xi_m(s)) dw_m(s), \quad (27)$$

$$\eta_m(t) = 1 + \int_0^t c_m^u(\xi_m(s)) \eta_m(s) ds, \quad (28)$$

where $w_m(t) \in R^d$ are independent Wiener processes and ξ_{0m} are independent r.v independent on $w_m(t)$ as well and having distributions μ_{0m} and use

$$\int_{R^d} \mathbf{h}(\mathbf{y}) \mathbf{u}_m(\mathbf{t}, \mathbf{y}) d\mathbf{y} = \mathbf{E} \left[\mathbf{h}(\xi_m(\mathbf{t})) \exp \left\{ \int_0^t \mathbf{c}_m(\mathbf{u}(\theta, \xi_m(\theta))) d\theta \right\} \right] \quad (29)$$

for closing relations similar to [15] where it was applied in a scalar case.

To justify this possibility we verify that (29) is equivalent to

$$\int_{R^d} h(y) u_m(t, y) dy = \int_{R^d} h(y) \left[\int_{R^d} p_m(0, x, t, y) u_m(0, x) dx + \int_0^t \int_{R^d} p_m(\theta, z_m, t, y) c_m^u(\theta, z) u_m(\theta, z) dz d\theta \right] dy. \quad (30)$$

where $p_m(0, x, t, y)$ is a density of a transition probability of the process $\xi_m(t)$ satisfying (27).

Assume that c_m and u_{0m} are bounded functions and consider $\mathbf{E} \left[\mathbf{h}(\xi_m(\mathbf{t})) \exp \left\{ \int_0^t \mathbf{c}_m(\mathbf{u}(\theta, \xi_m(\theta))) d\theta \right\} \right]$ as a linear bounded functional on the space $C_b(R^d)$. Applying Riesz theorem we get that there exists a measure $\nu_m(t)$ such that

$$\int_{R^d} \mathbf{h}(\mathbf{y}) \nu_m(\mathbf{t}, d\mathbf{y}) = \mathbf{E} \left[\mathbf{h}(\xi_m(\mathbf{t})) \exp \left\{ \int_0^t \mathbf{c}_m(\mathbf{u}(\mathbf{s}, \xi_m(\mathbf{s}))) d\mathbf{s} \right\} \right]. \quad (31)$$

To deduce (30) from (31) we note that the right hand side of (31) can be rewritten in the form

$$\begin{aligned}
 E[h(\xi_m(t))] + E \left[\int_0^t c_m(u(s, \xi_m(s))) \eta_m(s) E[h(\xi_m(t) | \xi_m(s))] ds \right] = \\
 = \int_{R^d} \int_{R^d} h(y) P_m(0, x, t, dy) \mu_{0,m}(dx) + \\
 + \int_0^t \int_{R^d} \int_{R^d} h(y) P_m(s, z, t, dy) c_m(u(s, z)) \nu_m(s, dz)
 \end{aligned}$$

and thus (31) has the form

$$\begin{aligned}
 \int_{R^d} h(y) \nu_m(t, y) dy = \int_{R^d} \int_{R^d} h(y) p_m(0, x, t, y) dy \mu_{0,m}(x) dx + \\
 + \int_0^t \int_{R^d} \left(\int_{R^d} p_m(s, z, t, y) h(y) dy \right) c_m(u(s, z)) \nu_m(s, z) dz ds.
 \end{aligned}$$

Here we have applied the Riesz theorem with test functions \mathbf{h} and $\mathbf{z} \rightarrow \int_{R^d} \mathbf{h}(\mathbf{y}) \mathbf{P}_m(\mathbf{s}, \mathbf{z}, \mathbf{t}, \mathbf{d}\mathbf{y}) \mathbf{c}_m(\mathbf{u}(\mathbf{s}, \mathbf{z}))$.

By definition the system (24), (25) has a mild solution $u = (u_1, u_2)$ with $u_1(t), u_2(t) \in L^2(R^d)$, $t \in [0, T]$ if $\forall h \in C_0^\infty(R^d)$ (30) holds.

Theorem 2. Assume that c_m are Borel bounded functions.

Functions $u_m \in L^1([0, T], W^1(R^d))$ are unique mild solutions of (24), (25) if and only if (29) holds, that is

$$\int_{R^d} \mathbf{h}(\mathbf{y}) \mathbf{u}_m(\mathbf{t}, \mathbf{y}) \mathbf{d}\mathbf{y} = \mathbf{E} [\mathbf{h}(\xi_m(\mathbf{t})) \eta_m(\mathbf{t})]$$

holds for any $h \in C_0^\infty(R^d)$.

We deduce from Th. 1 that (29) can be treated as an equation for the function $u_m(t, y)$ in a weak sense. This means that we can take

$$\begin{aligned} u_m(t, y) = & \int_{R^d} p_m(0, x, t, y) u_{0,m}(x) dx + \\ & + \int_0^t \int_{R^d} \int_{R^d} p_m(s, z, t, y) c_m(u(s, z)) u_m(s, z) dz ds \end{aligned} \quad (32)$$

as a closing relation for (27), (28).

Theorem 3. Let $A(x), c(u)$ satisfy conditions of Th. 1 and c is a bounded function. Assume $u_0 \in W^1(R^d)$. Then there exists a unique mild solution,

$u_m \in \mathcal{Q} = L^1([0, T], W^1(R^d)) \cap L^\infty([0, T], W^1(R^d))$ of the system

$$\frac{\partial u_m}{\partial t} = \frac{1}{2} M_m^2(y) \Delta u_m + c(u), \quad u_m(0, y) = u_{0m}(y), \quad m = 1, 2. \quad (33)$$

To prove this theorem we consider the equations (33), rewrite them as $u_m(t) = G_m(t, y, u)$ and prove that the map G is a contraction in \mathcal{Q} . To this end we first consider a couple of operators

$$U_m(s, t)\varphi(y) = \int_{R^d} p_m(s, x, t, y)\varphi(y)dy, \quad \varphi \in L^1(R^d) \cap L^\infty(R^d),$$

$$\begin{aligned} \Gamma_m v_m(t, y) = & \int_\tau^t \int_{R^d} p_m(\theta, z, t, y) c(v_m + U_m(\theta, t)\varphi(y)) \times \\ & \times (v_m + U_m(s, t)\varphi(z)) dx d\theta. \end{aligned}$$

We can verify that Γ_m acts in the space $L^1([t, t + \tau], B(0, K) \cap B_\infty(0, K))$ and is a contraction in norm of $W^1(R^d)$ for small enough τ . Here $B(0, K) \subset W^1(R^d)$ and $B_\infty(0, K) \subset L^\infty([t, t + \tau] \times R^d, R^2)$ for a small τ are centered balls with radius K . Then we know that $\exists v_m^0 \in \mathcal{Q}$ such that for $(t, y) \in [0, \tau] \times R^d$

$$v_m^0(t, y) = \int_0^t \int_{R^d} p_m(s, x, t, y) [v_m^0 + U_m u_{0m}](s, z) c_m(u(s, z)) dz ds$$

Setting $u_m^0(t) = v_m^0 + \int_{R^d} p_m(0, x, t, y) u_{0m}(x) dx$, we get

$$u_m^0(t, y) = \int_{R^d} p_m(0, x, t, y) u_{0m}(x) dx + \int_0^t ds \int_{R^d} p_m(s, z, t, y) u_m^0(s, z) c_m(u^0(s, z)) dz.$$

Consider a partition

$0 \leq \tau \leq 2\tau \leq \dots \leq k\tau \leq (k+1)\tau \leq \dots \leq N\tau = T$. We have proved that $\exists!$ a solution of the system for $s, t \in [r\tau, [r+1]\tau]$

$$u_m^k(t, y) = \int_{R^d} p_m(k\tau, z, t, y) u^{k-1}(k\tau, z) dz + \\ + \int_{k\tau}^t \int_{R^d} p_m(s, z, t, y) u^k(s, z) c_m(u^k(s, z)) dz ds,$$

$$v_m^k(t, y) = \int_{k\tau}^t \int_{R^d} p_m(s, z, t, y) [v^k(s, z) + U_m^k u_0(s, z)] c_m(u^k(s, z)) dz ds,$$

for $t \in [k\tau, (k+1)\tau]$. Setting $u^k = U^k u_0 + v^k$ we get

$$u_m^k(t, y) = \int_{R^d} p_m(s, z, t, y) u^{k-1}(k\tau, z) dz + \\ + \int_{k\tau}^t \int_{R^d} p_m(s, z, t, y) u^k(s, z) c(u^k, \nabla u^k) dz.$$

Next we define $u_m : [0, T] \times R^d \rightarrow R^d$ setting $u_m = u_m^k$ on each

Consider one more example of a system of type (2), namely SKT system

$$\frac{\partial u_m}{\partial t} = \Delta(u_m[\alpha_m + \alpha_{m1}u_1 + \alpha_{m2}u_2]) + [c_{m0} + c_{m1}u_1 + c_{m2}u_2]u_m, \quad (34)$$

$$u_m(0, x) = u_{0m}(x), \quad m = 1, 2,$$

We associate to this system a stochastic system of the form

$$d\xi_m(t) = M_m^u(\xi_m(t))dw(t), \quad \xi_m(0) = \xi_{0m}, \quad (35)$$

$$d\eta_m(t) = c_m^u(\xi_m(t))\eta_m(t)dt, \quad \eta_m(0) = 1, \quad (36)$$

where $M_m^u = \sqrt{\alpha_m + \alpha_{m1}u^1 + \alpha_{m2}u^2}$, $c_m^u = c_{m0} + c_{m1}u^1 + c_{m2}u^2$. In order to obtain a closing relation we mollify this system and obtain a system of McKean-Vlasov type equations. Given a finite Borel measure $\mu(dx)$ (or its density $u(x)$) on R^d we denote by $\rho_\epsilon * \mu$ the convolution

$$[\rho_\epsilon * \mu](y) = \int_{R^d} \rho_\epsilon(y - x)\mu(dx) = \int_{R^d} \rho_\epsilon(y - x)u(x)dx$$

Let

$$M_{m,\epsilon}^u(t, y) = \int_{R^d} \rho_\epsilon(y - x_1)[1 + \alpha_{m1}u^1(t, x_1) + \alpha_{m2}u^2(t, x_1)]dx_1,$$

$$c_{m,\epsilon}^u(t, y) = \int_{R^d} \rho_\epsilon(y - x_1)[c_{m0} + c_{m1}u^1(t, x_1) + c_{m2}u^2(t, x_1)]dx_1$$

denote mollifications of coefficients $M_m^u(t, x)$, $c_m^u(t, x)$ for a fixed $\epsilon > 0$. Setting $\mu_m(t, dy) = u^m(t, y)dy$ we may consider the above relations as relations for

$M_{m,\epsilon} : [0, T] \times R^d \times [C([0, T]; \mathcal{P}_1(R^d)) \times C([0, T]; \mathcal{P}_1(R^d))] \rightarrow R$
and

$c_{m,\epsilon} : [0, T] \times R^d \times [C([0, T]; \mathcal{P}_1(R^d)) \times C([0, T]; \mathcal{P}_1(R^d))] \rightarrow R$
and set

$$M_{m,\epsilon}^\mu(t, y) = \int_{R^d} \rho_\epsilon(y - x_1)[1 + \alpha_{m1}\mu^1(t, dx_1) + \alpha_{m2}\mu^2(t, dx_1)],$$

$$c_{m,\epsilon}^\mu(t, y) = \int_{R^d} \rho_\epsilon(y - x_1)[c_{m0} + c_{m1}\mu^1(t, x_1) + c_{m2}\mu^2(t, x_1)].$$

Note that due to properties of ρ_ϵ we know that $M_{m,\epsilon}^\mu(t, y)$, $c_{m,\epsilon}^\mu(t, y)$ are bounded and Lipschitz continuous with respect to y uniformly with respect to μ_m for each $\epsilon > 0$, that is for $y \in R^d$ there exists a constant $K > 0$ such that

$$|M_{m,\epsilon}(t, y, \mu)| \leq K \quad \text{and} \quad |c_\epsilon(t, y, \mu)| \leq K, \forall \mu \in C([0, T]; \mathcal{P}_1(R^d)).$$

With these notations the mollification of system (31) can be written in the form

$$\frac{\partial \mu_m}{\partial t} = \frac{1}{2} \Delta [M_{m,\epsilon}^2(t, y, \mu) \mu_m] + c_{m,\epsilon}(t, y, \mu) \mu_m, \quad \mu_m(0, dy) = \mu_{0m}(dy), \quad (37)$$

as a system for $\mu_m \in C([0, T]; \mathcal{P}_1(R^d))$.

Theorem 4. *A stochastic counterpart of (34) has the form*

$$d\xi_m^\epsilon(t) = M_{m,\epsilon}(t, \xi_m^\epsilon(t), \mu)dw_m(t), \quad \xi_m^\epsilon(0) = \xi_{0m}, \quad (38)$$

with $\mathcal{L}(\xi_{0m}) = P\{\xi_{0m} \in dy\} = \mu_{0m}(dy)$

$$d\eta_m^\epsilon = \mathbf{c}_{m,\epsilon}(\mathbf{t}, \xi_m^\epsilon(\mathbf{t}), \mu)\eta_m^\epsilon(\mathbf{t})d\mathbf{t}, \quad \eta_m(0) = \mathbf{1}. \quad (39)$$

$$\int_{\mathbf{R}^d \times \mathbf{R}^d} \mathbf{h}(\mathbf{y})\mu_m^\epsilon(\mathbf{t}, d\mathbf{y}) = \mathbf{E}[\eta_m^\epsilon(\mathbf{t})\mathbf{h}(\xi_m^\epsilon(\mathbf{t}))]. \quad (40)$$

As a final example, we consider the MHD-Burgers system which can be rewritten in the form

$$\frac{\partial \mathbf{u}_m}{\partial t} = \frac{1}{2} \text{Tr} \nabla^2 [\mathbf{A}_m^2(\mathbf{x}) \mathbf{u}_m] + \mathbf{c}_m^u(t, \mathbf{y}) \mathbf{u}_m, \quad \mathbf{u}_m(0, \mathbf{y}) = \mathbf{u}_{0m}(\mathbf{y}). \quad (41)$$

w.r.t. $u = (v, B) \in R^6$ $u_i = v_i, u_{3+i} = B_i, i = 1, 2, 3, c_m^u(t, y) = c_m(u(t, y), \nabla u(t, y)), A_m^2 = A_m A_m^*$,

$$A_1 = A_2 = A_3 = \sigma, \quad A_4 = A_5 = A_6 = \mu,$$

$$c_1^u = \frac{1}{u_1} [u_4 \nabla_3 u_6 - u_6 \nabla_1 u_6 - u_5 \nabla_1 u_5 + u_5 \nabla_2 u_4 - \sum_{i=1}^3 \nabla_i u_1], \dots$$

$$c_4^u = \frac{1}{u_4} [\nabla_2 [u_1 u_5 - u_2 u_4] - \nabla_3 [u_1 u_6 - u_3 u_4]], \dots$$

e.t.c.

A function $u : [0, T] \times R^d \rightarrow R^{d_1}$, $u = (u_1, \dots, u_{d_1})$, $u_m(t) \in W_{loc}^{1,1}(R^d)$, $t \in [0, T]$, with $d = 3$, $d_1 = 6$, is a weak solution of (38), if for any $h \in C_0^\infty(R^d)$

$$\begin{aligned} \int_{R^d} u_m(t, y) h(y) dy &= \int_{R^d} u_{0m}(y) h(y) dy + \int_0^t \int_{R^d} u_m(\theta, z) \mathcal{L}_m h(z) dz d\theta + \\ &+ \int_0^t \int_{R^d} u_m(\theta, z) c_m^u(\theta, z) h(z) dz d\theta. \end{aligned} \quad (42)$$

where $\mathcal{L}_m h = \frac{1}{2} \text{Tr} A_m^2(x) \nabla^2 h$. As above a mild solution of (38) is defined by an integral identity valid for any $h \in C_0^\infty(R^d)$

$$\begin{aligned} \int_{R^d} h(y) u_m(t, y) dy &= \int_{R^d} h(y) \left(\int_{R^d} p_m(0, x, t, y) u_{0m}(x) dx \right) + \\ &+ \int_{[0, T] \times R^d} \left(\int_{R^d} h(y) p_m(\theta, z, t, y) dy \right) c_m^u(\theta, z) u_m(\theta, z) dz d\theta. \end{aligned}$$

A stochastic problem associated with (41) has the form

$$\xi_m(t) = \xi_{0m} + \int_0^t A_m(\xi_m(\theta)) dw_m(\theta), \quad (43)$$

$m = 1, \dots, 6,$

$$\eta_m(t) = 1 + \int_0^t c_m(u(\theta, \xi_m(\theta)), \nabla u(\theta, \xi_m(\theta))) \eta_m(\theta) d\theta. \quad (44)$$

where ξ_{0m} are independent r.v. which do not depend on

$w(t) = (w_1(t), \dots, w_{d_1}(t))$ and

$P\{\xi_{0m} \in dy\} = \mu_{0m}(dy) = u_{0m}(y)dy.$

$$\int_{R^d} h(y) \mu_m(t, dy) = \mathbf{E} [h(\xi_m(t)) \eta_m(t)]. \quad (45)$$

Let $c_m(u, v)$ be a bounded function for $u \in R_1^d, v \in R^d \otimes R^{d_1}$ then similar to above we use

$$\int_{R^d} h(y) \mu_m(t, dy) = E \left[h(\xi_m(t)) \exp \left\{ \int_0^t c_m^v(\theta, \xi_m(\theta)) d\theta \right\} \right]$$

to define closing relations.

Let $v_m \in C([0, T], W^{1,1}(R^d))$ be given and $\xi_m(t)$ solves (39). Then (45) defines a unique mild measure valued solution μ_m of

$$\frac{\partial \mu_m}{\partial t} = \frac{1}{2} \text{Tr} \nabla^2 [A_m^2(y) \mu_m] + c_m(v, \nabla v) \mu_m, \quad (46)$$

$$\mu_m(0, dy) = \mu_{0m}(dy).$$

We can verify that given u , the measure $\mu_m(t)$ defined by (45) satisfies an integral equation

$$\begin{aligned} \mu_m(t, dy) = & \int_{R^d} \mu_{0m}(dx) P_m(0, x, t, dy) + \\ & \int_0^t \int_{R^d} c_m^u(\theta, z) P_m(\theta, z, t, dy) \mu_m(\theta, dz) d\theta. \end{aligned} \quad (47)$$

where $P_m(0, \xi_0, t, dy) = P\{\xi_{0, \xi_0}(t) \in dy\}$.

To satisfy the condition that $c(u, v)$ is bounded we mollify (38) and consider a system

$$\frac{\partial \mu_{\epsilon, m}}{\partial t} = \frac{1}{2} \text{Tr} \nabla^2 [M_m^2(y) \mu_{\epsilon, m}] + c_m^{\rho_\epsilon * \mu}(t, y) \mu_{\epsilon, m} \quad (48)$$

$$\mu_{\epsilon, m}(0, dy) = \mu_{0m}(dy),$$

where $c_m^{\rho_\epsilon * \mu}(t, y) = c_m([\rho_\epsilon * \mu](t, y), [\nabla \rho_\epsilon * \mu](t, y))$, and an associated system of stochastic equations

$$\xi_m(t) = \xi_{m0} + \int_0^t A_m(\xi_m(\theta)) dw_m(\theta), \quad (49)$$

$$\eta_{\epsilon, m}(t) = 1 + \int_0^t c_m([\rho_\epsilon * \mu](\theta, \xi_m(\theta)), [\nabla \rho_\epsilon * \mu](\theta, \xi_m(\theta))) \eta_{\epsilon, m}(\theta) d\theta, \quad (50)$$

$$\int_{R^d} h(y) \mu_{\epsilon, m}(t, dy) = \mathbf{E} [h(\xi_m(t)) \eta_{\epsilon, m}(t)] \quad (51)$$

$\forall h \in C_b(R^d), t \in [0, T]$.

C 1. Let $A_m \in C^3$ and bounded, $u_{0m}(dy)$ be a Borel measure with a density $u_{0m}(y)$, and $c_m : R^{d_1} \times R^d \otimes R^{d_1} \rightarrow R$ satisfy

$$|c_m(u, v)| \leq K[1 + \|u\|^2 + \|v\|^2],$$

$$|c_m(u, v) - c_m(u_1, v_1)| \leq L_{u,v}[\|u - u_1\| + \|v - v_1\|].$$

Lemma 5. Let **C1** holds, $\xi_m(t)$ solve (41), $\eta_m(t)$ solve (45) and $u_m(t) \in W^{1,1}(R^d) \cap C^1(R^d)$ is a given function. Then $\mu_{\epsilon,m}(t)$ is a mild measure valued solution of (48) iff for all $h \in C_0^\infty(R^d)$ (51) holds.

To prove the existence and uniqueness of a solution to (48) we consider the space $\mathcal{M}^{d_1}(R^d) = \bigoplus_{k=1}^{d_1} \mathcal{M}_k(R^d)$ with the norm $\|\mu\|_{TV} = \sum_{m=1}^{d_1} \|\mu_m\|_{TV}$.

Let $\mathcal{M}(R^d)$ be the space of bounded Borel measures,
 $\mathcal{N}([\theta, \theta + \tau], \mathcal{M}(R^d))$ ($\mathcal{N}([\theta, \theta + \tau], \mathcal{M}^{d_1}(R^d))$) be the space of
 bounded maps defined on $[\theta, \theta + \tau]$ valued in $\mathcal{M}^{d_1}(R^d)$ (in
 $\mathcal{M}^{d_1}(R^d)$), equipped with total variation norm $\|\cdot\|_{TV}$.

$$\|\mu_m\|_{TV} = \sup_{h \in C_b(R^d), \|h\|_\infty \leq 1} \left| \int_{R^d} h(x) \mu_m(dx) \right|$$

Let $B^{d_1}(0, K)$ ($B(0, r)$) a centered ball with radius K (r) in
 $\mathcal{M}^{d_1}(R^d)$ (in $\mathcal{M}(R^d)$) and let
 $\mathcal{N}([\theta, \theta + \tau], B^{d_1}(0, K)) \subset \mathcal{N}([\theta, \theta + \tau], \mathcal{M}^{d_1}(R^d))$ denotes a
 closed subset of maps from $[\theta, \theta + \tau]$ to $B^{d_1}(0, K)$.

We consider maps

$$U_m(t) : \kappa_m \in \mathcal{M}(R^d) \mapsto U_m(t)\kappa_m \in \mathcal{N}([s, s + \tau], \mathcal{M}(R^d))$$

given by

$$[U_m(t)\kappa_m](t, dy) = \int_{R^d} P_m(0, x, t, dy)\kappa_m(dx), \quad t \in [s, s + \tau]$$

and $\Gamma_\epsilon : \mu \mapsto \Gamma_\epsilon\mu$, $\mu \in \mathcal{N}([s, s + \tau], \mathcal{M}^{d_1}(R^d))$, $t \in [s, s + \tau]$
given by

$$\begin{aligned} [\Gamma_\epsilon\mu]_m(t, dy) &= \int_0^t \int_{R^d} P_m(s, z, t, dy) c_m([\rho_\epsilon * \tilde{\mu}](\theta, z), [\nabla \rho_\epsilon * \tilde{\mu}](s, z)) \times \\ &\quad \times [\mu + U\kappa]_m(s, dz) ds, \end{aligned}$$

where $m = 1, \dots, d_1$, $\tilde{\mu} = \mu + U\kappa$ and
 $[\rho_\epsilon * \tilde{\mu}](\theta, z) = ([\rho_\epsilon * \tilde{\mu}]_1(\theta, z), \dots, [\rho_\epsilon * \tilde{\mu}]_{d_1}(\theta, z))$.

Theorem 6. Let **C 1** hold and for given $r > 0, \epsilon > 0$ the estimates $\|\mu_{0m}\|_{TV} \leq r$ and $\max_{\nu \in B(0,r)} |c_m(\nu_\epsilon, \nabla \nu_\epsilon)| \leq K_c^\epsilon$ hold. Then there exist $K > 0$ and $\tau > 0$ such that the map Γ_ϵ is a contraction in $\mathcal{N}([s, s + \tau], B^{d_1}(0, K))$.

Let $0 = t_0 \leq t_1 \leq \dots \leq t_n = T$ be a partition of $[0, T]$, $\tau = \frac{T}{n}$.

Theorem 7. Assume **C 3.1**. For fixed $\epsilon > 0$ $\mu_m^\epsilon : [0, \tau] \rightarrow \mathcal{M}(R^d)$ satisfy

$$\begin{aligned} \mu_{\epsilon,m}(t, dy) &= \int_{R^d} P_m(k\tau, z, t, dy) \mu_{\epsilon,m}(k\tau, dz) + \\ &+ \int_{k\tau}^t \int_{R^d} P_m(s, z, t, dy) c_m^{\mu_\epsilon}(s, z) \mu_{\epsilon,m}(s, dz) ds \end{aligned}$$

iff






$$\begin{aligned} \mu_m^\epsilon(t, dy) &= \int_{R^d} P_m(0, x, t, dy) \mu_0(dx) + \\ &+ \int_0^t \int_{R^d} P_m(s, z, t, dy) c_m^{\mu_\epsilon}(s, z) \mu_m^\epsilon(s, dz) ds. \end{aligned}$$






In addition μ_m^ϵ is a unique mild solution of (48).






Theorem 8. *Let C 1 hold and u_m^ϵ is a density of a solution $\mu_m^\epsilon(t)$ to (48)*

$$u_{\epsilon,m}(t, y)dy = \mu_m^\epsilon(t, dy).$$

Then functions $u_{\epsilon,m}(t, \cdot)$ converge to a mild solution $u_m(t, \cdot)$, of (41) in the norm of $W^{1,1}(R^d)$.

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